

# A NEW WAY TO SCAN THE WORLD

A new way to "look" at the world around you.

With 320,000 points per second, S1 catches high-quality scans hands down.

With industry-leading SLAM algorithm, S1 captures, processess, and displays accurate point clouds on the mobile terminal in real time.



320,000 Points Per Second



0.8-2 cm



16 Sensors



120 m



Real-Time Point Cloud



Indoor & Outdoor Scanning



Lightweight and More Portable



Dual Battery Hot-Swappable

# **APPLICATION SCENARIOS**

Indoor, ourdoor, and even underground without a GNSS receiver.











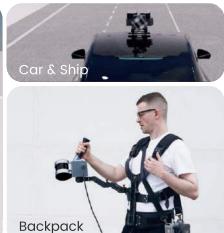


## AS VERSATILE AS IT IS PORTABLE

Lightweight design for easy portability.

Real-time point cloud display and SLAM processing.







## YOUR POINT CLOUD STUDIO



### TRION SCAN

#### Real-time Visualization of 3D Point Cloud Software

- Displays the scanned project files, storage capacity, and battery life
- Visualizes the point cloud in real time
- Tracks real-time path
- Manages and downloads project files

### TRION METAHUB

#### Point Cloud Post-Process Software

- Denoises and colorizes point clouds
- Stitches point clouds, maps shadow, transforms coordinates, and does automatic plane fitting
- Classifies point clouds, produces 2D drawings\*, and builds 3D models\*



## **SPECS**

Range

120 m

**FOV** 

360°×270°

Points per Second

320,000

Display

Real-time preview on mobile terminal

Datalogger Weight (incl. single battery)

2.2 kg

**Battery Life** (Dual battery)

4 hours

**Ingress Protection** 

IP54

Sensors

16

**Laser Class** 

Class  $1/\lambda$  905 nm

Accuracy

0.8 - 2 cm

**Processing** 

Real-time

Carrier

Backpack or shoulder strap

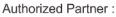
**Scanner Weight** 

1.8 kg

**Storage Capacity** 

512 GB







Jakarta

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### CREATE FOR A BETTER WORLD

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